

S-Expansion of Higher-Order Lie Algebras

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Abstract

By means of a generalization of the S-expansion method we construct a procedure to obtain expanded higher-order Lie algebras. It is shown that the direct product between an Abelian semigroup S and a higher-order Lie algebra $(\mathcal{G}, [, ...,])$ is also a higher-order Lie algebra. From this S-expanded Lie algebra are obtained resonant submultialgebras and reduced multialgebras of a resonant submultialgebra.

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I. INTRODUCTION

Higher-order (or multibracket) simple Lie algebras [1], [2], [3] are generalized ordinary Lie algebras. Their structure constants are given by Lie algebra cohomology cocycles which, by virtue of being such, satisfy a suitable generalization of the Jacobi identity.

As is noted in ref [1], [3] it could be interesting to find applications of these higher-order Lie algebras to know whether the cohomological restrictions which determine and condition their existence have a physical significance. Lie algebra cohomology arguments have already been very useful in various physical problems as in the description of anomalies or in the construction of the Wess-Zumino terms required in the action of extended supersymmetric objects. Other questions may be posed from a purely mathematical point of view. From the discussion in Sect.4 of ref. [1] we know that a representation of a simple Lie algebra may not

be a representation for the associated higher-order Lie algebras. Thus, the representation theory of higher-order algebras requires a separate analysis. A very interesting open problem from a structural point of view is the expansions of higher-order Lie algebras, which will take us outside the domain of the simple ones.

The purpose of this paper is to show that the S-expansion method developed in ref. [4] (see also [5],[6], [7]) can be generalized so that it permits obtaining expanded higher-order Lie algebras.

The paper is organized as follows: In section 2 we shall review some aspects of higher-order Lie algebras. The main point of this section is to display the differences between ordinary Lie algebras and higher-order Lie algebras and to generalize the definitions of higher-order Lie subalgebras and higher-order reduced Lie algebras. In section 3 we generalize the S-expansion method and we show that it is possible to obtain higher-order expanded Lie algebras. In section 4 is shown that, under determined conditions, relevant higher-order Lie subalgebras can be extracted from the S-expanded higher-order Lie algebras.

II. HIGHER-ORDER LIE ALGEBRAS

In this section we shall review some aspects of higher-order Lie algebras. The main point of this section is to display the differences between ordinary Lie algebras and higher-order Lie algebras and to generalize the concepts of subalgebra and reduced Lie algebra of ref. [4].

Definition 1 *An algebra is defined as a pair (G, \bullet) where G is a finite dimensional vector space, and $\bullet : G \times G \rightarrow G$ is a rule of composition defined over the vector space.*

Definition 2 *A Lie algebra \mathcal{G} is defined by the pair $(G, [,])$ where G is a finite dimensional vector space, with basis $\{T_A\}_{A=1}^{\dim G}$, over the field K of real or complex numbers; and $[,]$ is a rule of composition $(T_{A_1}, T_{A_2}) \rightarrow [T_{A_1}, T_{A_2}] \in G$ which satisfies the following axioms:*

- $[\alpha T_{A_1} + \beta T_{A_2}, T_{A_3}] = \alpha [T_{A_1}, T_{A_3}] + \beta [T_{A_2}, T_{A_3}]$ for $\alpha, \beta \in K$ (linearity),
- $[T_{A_1}, T_{A_2}] = -[T_{A_2}, T_{A_1}] \quad \forall T_{A_1}, T_{A_2} \in G$ (antisymmetry),
- $[[T_{A_1}, T_{A_2}], T_{A_3}] + [[T_{A_2}, T_{A_3}], T_{A_1}] + [[T_{A_3}, T_{A_1}], T_{A_2}] = 0,$
for all $T_{A_1}, T_{A_2}, T_{A_3} \in G$ (Jacobi identity).

The Jacobi identity (JI) can be re-written

$$\frac{1}{1!} \frac{1}{2!} \sum_{\sigma \in S_3} (-1)^{\pi(\sigma)} \left[\left[T_{A_{\sigma(1)}}, T_{A_{\sigma(2)}} \right], T_{A_{\sigma(3)}} \right] = 0. \quad (1)$$

where S_3 is the permutation group of three elements and $\pi(\sigma)$ is the parity of the permutation σ .

Definition 3 Let \mathcal{G} be a Lie algebra. A n -bracket $[\dots]$ or skew-symmetric Lie multibracket is a Lie algebra valued n -linear skew-symmetric mapping $[\dots] : \mathcal{G} \times \dots \times \mathcal{G} \rightarrow \mathcal{G}$,

$$(T_{A_1}, \dots, T_{A_n}) \rightarrow [T_{A_1}, \dots, T_{A_n}] = C_{A_1 \dots A_n}^B T_B \quad (2)$$

where the constants $C_{A_1 \dots A_n}^B$ are called higher-order structure constants which are completely antisymmetric in the indices $A_1 \dots A_n$.

To define higher-order Lie algebras we need to find the generalization of the Jacobi identity. We postulate that the generalization of the left hand side of eq. (1) is given by

$$\frac{1}{(n-1)!} \frac{1}{n!} \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[\left[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}} \right], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] \quad (3)$$

However we must find the conditions under which is possible the vanishing of the right hand side. Let T_A be the basis of the algebra in a representation of \mathcal{G} . Then is possible to realize the multibracket as

$$\begin{aligned} [T_{A_1}, \dots, T_{A_n}] &= \varepsilon_{A_1 \dots A_n}^{B_1 \dots B_n} T_{B_1} \dots T_{B_n} \\ &= \sum_{\sigma \in S_n} (-1)^{\pi(\sigma)} T_{A_{\sigma(1)}} \dots T_{A_{\sigma(n)}}, \end{aligned} \quad (4)$$

where S_n is the permutation group of n element and $\pi(\sigma)$ is the parity of the permutation σ . In the appendix we will show that the realization (4) of the multibracket satisfy the identity

$$\begin{aligned} &\frac{1}{(n-1)!} \frac{1}{n!} \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[\left[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}} \right], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] \\ &= \begin{cases} 0 & , n \text{ even} \\ n [T_{A_1}, \dots, T_{A_{2n-1}}] & , n \text{ odd.} \end{cases} \end{aligned} \quad (5)$$

This means that is possible to obtain a generalization of the Jacobi identity for n even. For n odd we obtain an identity which contains a combination of multibrackets of different orders. Thus we can postulate that [1]

$$\frac{1}{(n-1)!} \frac{1}{n!} \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[\left[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}} \right], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] = 0, \quad (6)$$

is the appropriate generalization of the Jacobi Identity for n even. This identity implies the following condition on the structure constants $C_{A_1 \dots A_n}^B$:

$$\varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} C_{B_1 \dots B_n}^C C_{CB_{n+1} \dots B_{2n-1}}^D = 0 \quad (7)$$

which is the generalization of the Jacobi condition [1].

By analogy with the standard Lie algebra, we may now give the following definition [1]:

Definition 4 *Let \mathcal{G} be a Lie algebra and let n be even. A higher-order Lie algebra or multialgebra on \mathcal{G} is the algebra defined by the pair $(\mathcal{G}, [\dots])$ where the multibracket $[\dots]$ (2) is multilinear, antisymmetric and satisfies the generalized Jacobi identity (6); and where the higher-order structure constants satisfy the generalized Jacobi condition (7).*

The following definition generalizes the concept of Subalgebra:

Definition 5 (Submultialgebra): *Let $(\mathcal{G}, [\dots])$ be a multialgebra, and consider the Lie algebra \mathcal{G} of the form $\mathcal{G} = V_0 \oplus V_1$. The subspace $(V_0, [\dots])$ will be called a submultialgebra of $(\mathcal{G}, [\dots])$ if it satisfies*

$$[V_0, V_0, \dots, V_0] \subset V_0. \quad (8)$$

The existence of submultialgebras is reflected in certain definite restrictions on the structure constants. Let $C_{A_1 \dots A_n}^B$ be the generalized structure constants of the multialgebra $(\mathcal{G}, [\dots])$. If $\{T_{A_i}\}$, $\{T_{a_i^0}\}$ and $\{T_{a_i^1}\}$ denote the bases of \mathcal{G} , V_0 and V_1 respectively, where $A_i = 1, \dots, \dim \mathcal{G}$, $a_i^0 = 1, \dots, \dim V_0$ and $a_i^1 = \dim V_0 + 1, \dots, \dim \mathcal{G}$, then the condition (8) can be expressed as

$$C_{a_1^0 \dots a_n^0}^{b^1} = 0 \quad (9)$$

for $a_1^0 \dots a_n^0 \leq \dim V_0$ and $b^1 \geq \dim V_0 + 1$. In fact, If V_0 is a submultialgebra then $[V_0, V_0, \dots, V_0] \subset V_0$. This mean that

$$[T_{a_1^0}, \dots, T_{a_n^0}] = C_{a_1^0 \dots a_n^0}^{b^0} T_{b^0}. \quad (10)$$

i.e. for $\dim V_0 < b^1 < \dim G$ we have $C_{a_1^0 \dots a_n^0}^{b^1} = 0$.

The following theorem generalizes the concept of reduction of Lie algebras of ref. [4] to higher-order Lie algebras.

Theorem 6 (*Reduced Multialgebra*): Let $(\mathcal{G}, [, \dots,])$ be a multialgebra, and consider the Lie algebra G of the form $G = V_0 \oplus V_1$, with $\{T_{A_i}\}$ being a basis for G , $\{T_{a_i^0}\}$ a basis for V_0 and $\{T_{a_i^1}\}$ a basis for V_1 . If the condition

$$[V_1, V_0, \dots, V_0] \subset V_1, \quad (11)$$

is satisfied, then the structure constants $C_{e^1 B_{n+1} \dots B_{2n-1}}^{d^0}$ are zero, which lead to that the structure constants $C_{a_1^0 \dots a_n^0}^{b^0}$ satisfy the generalized Jacobi condition by themselves, and therefore

$$[T_{a_1^0}, \dots, T_{a_n^0}] = C_{a_1^0 \dots a_n^0}^{b^0} T_{b^0} \quad (12)$$

corresponds by itself to a high-order Lie algebra. This algebra, with structure constants $C_{a_1^0 \dots a_n^0}^{b^0}$, is called a reduced multialgebra of $(\mathcal{G}, [, \dots,])$ and is symbolized as $|V_0, [, \dots,]|$.

Proof. If the condition

$$[V_1, V_0, \dots, V_0] \subset V_1$$

is satisfied, we have

$$\begin{aligned} [T_{a_1^0}, \dots, T_{a_n^0}] &= C_{a_1^0 \dots a_n^0}^{b^0} T_{b^0} + C_{a_1^0 \dots a_n^0}^{b^1} T_{b^1} \\ [T_{b^1 a_1^0}, \dots, T_{a_{n-1}^0}] &= C_{b^1 a_1^0 \dots a_{n-1}^0}^{c^1} T_{c^1} \\ [T_{b_1^1}, \dots, T_{b_n^1}] &= C_{b_1^1 \dots b_n^1}^{c^0} T_{c^0} + C_{b_1^1 \dots b_n^1}^{c^1} T_{c^1} \end{aligned} \quad (13)$$

The structure constant of G satisfy the Jacobi identity

$$\varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} C_{B_1 \dots B_n}^C C_{CB_{n+1} \dots B_{2n-1}}^D = 0. \quad (14)$$

If $\mathcal{G} = V_0 \oplus V_1$ y $\{T_{A_i}\}$, $\{T_{a_i^0}\}$, y $\{T_{a_i^1}\}$ are the corresponding bases of \mathcal{G} , V_0 , y V_1 (where $A_i = 1, \dots, \dim \mathcal{G}$, $a_i^0 = 1, \dots, \dim V_0$ and $a_i^1 = \dim V_0 + 1, \dots, \dim \mathcal{G}$), then the generalized Jacobi condition on V_0 is given by

$$\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{B_1 \dots B_{2n-1}} C_{B_1 \dots B_n}^E C_{EB_{n+1} \dots B_{2n-1}}^{d^0} = 0 \quad (15)$$

which can be re-written as

$$\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{B_1 \dots B_{2n-1}} C_{B_1 \dots B_n}^{e^0} C_{e^0 B_{n+1} \dots B_{2n-1}}^{d^0} + \varepsilon_{a_1^0 \dots a_{2n-1}^0}^{B_1 \dots B_{2n-1}} C_{B_1 \dots B_n}^{e^1} C_{e^1 B_{n+1} \dots B_{2n-1}}^{d^0} = 0. \quad (16)$$

We consider now the indices $B_1 \dots B_{2n-1}$. If one of these indices takes on a value in V_1 , we have

$$\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{b_1^1 b_2^0 \dots b_{2n-1}^0} = \begin{vmatrix} \delta_{a_1^0}^{b_1^1} & \delta_{a_1^0}^{b_2^0} & \dots & \delta_{a_1^0}^{b_{2n-1}^0} \\ \delta_{a_2^0}^{b_1^1} & \delta_{a_2^0}^{b_2^0} & \dots & \delta_{a_2^0}^{b_{2n-1}^0} \\ \vdots & \vdots & \ddots & \vdots \\ \delta_{a_{2n-1}^0}^{b_1^1} & \delta_{a_{2n-1}^0}^{b_2^0} & \dots & \delta_{a_{2n-1}^0}^{b_{2n-1}^0} \end{vmatrix} = \begin{vmatrix} 0 & \delta_{a_1^0}^{b_2^0} & \dots & \delta_{a_1^0}^{b_{2n-1}^0} \\ 0 & \delta_{a_2^0}^{b_2^0} & \dots & \delta_{a_2^0}^{b_{2n-1}^0} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \delta_{a_{2n-1}^0}^{b_2^0} & \dots & \delta_{a_{2n-1}^0}^{b_{2n-1}^0} \end{vmatrix} = 0. \quad (17)$$

From (17) we can see that a column of the determinant is zero and therefore $\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{b_1^1 b_2^0 \dots b_{2n-1}^0} = 0$. Similarly, any permutation on the set $(b_1^1 b_2^0 \dots b_{2n-1}^0)$ in $\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{b_1^1 b_2^0 \dots b_{2n-1}^0}$ will be null. If two indices of the set $(B_1 \dots B_{2n-1})$ take on values in V_1 , we have

$$\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{b_1^1 b_2^1 b_3^0 \dots b_{2n-1}^0} = \begin{vmatrix} \delta_{a_1^0}^{b_1^1} & \delta_{a_1^0}^{b_2^1} & \delta_{a_1^0}^{b_3^0} & \dots & \delta_{a_1^0}^{b_{2n-1}^0} \\ \delta_{a_2^0}^{b_1^1} & \delta_{a_2^0}^{b_2^1} & \delta_{a_2^0}^{b_3^0} & \dots & \delta_{a_2^0}^{b_{2n-1}^0} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \delta_{a_{2n-1}^0}^{b_1^1} & \delta_{a_{2n-1}^0}^{b_2^1} & \delta_{a_{2n-1}^0}^{b_3^0} & \dots & \delta_{a_{2n-1}^0}^{b_{2n-1}^0} \end{vmatrix} = \begin{vmatrix} 0 & 0 & \delta_{a_1^0}^{b_3^0} & \dots & \delta_{a_1^0}^{b_{2n-1}^0} \\ 0 & 0 & \delta_{a_2^0}^{b_3^0} & \dots & \delta_{a_2^0}^{b_{2n-1}^0} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \delta_{a_{2n-1}^0}^{b_3^0} & \dots & \delta_{a_{2n-1}^0}^{b_{2n-1}^0} \end{vmatrix} = 0. \quad (18)$$

From (18) we can see that a column of the determinant is zero and therefore $\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{b_1^1 b_2^1 b_3^0 \dots b_{2n-1}^0} = 0$. In general the number of null columns increase with the number of indices of the set $(B_1 \dots B_{2n-1})$, which take on values in V_1 . Thus, the equation (16) is then given by

$$\varepsilon_{a_1^0 \dots a_{2n-1}^0}^{b_1^0 \dots b_{2n-1}^0} C_{b_1^0 \dots b_n^0}^{e^0} C_{e^0 B_{n+1} \dots B_{2n-1}}^{d^0} + \varepsilon_{a_1^0 \dots a_{2n-1}^0}^{b_1^0 \dots b_{2n-1}^0} C_{b_1^0 \dots b_n^0}^{e^1} C_{e^1 B_{n+1} \dots B_{2n-1}}^{d^0} = 0. \quad (19)$$

From (19) we can see that the structure constant $C_{a_1^0 \dots a_n^0}^{b^0}$ satisfy the generalized Jacobi identity by themselves in two cases: ■

- When $C_{b_1^0 \dots b_n^0}^{e^1} = 0$, i.e., when V_0 is a submultialgebra
- When $C_{e^1 B_{n+1} \dots B_{2n-1}}^{d^0} = 0$, i.e., when $[V_1, V_0, \dots, V_0] \subset V_1$. This means that in this case the structure constant $C_{a_1^0 \dots a_n^0}^{b^0}$ satisfy the generalized Jacobi identity and

$$[T_{a_1^0}, \dots, T_{a_n^0}] = C_{a_1^0 \dots a_n^0}^{b^0} T_{b^0} \quad (20)$$

correspond by itself to a higher order Lie algebra. It is interesting to note that a reduced multialgebra $|V_0, [, \dots,]|$ does not correspond to a submultialgebra of $(\mathcal{G}, [, \dots,])$.

Definition 7 The Lie multialgebra obtained from the condition $[V_1, V_0, \dots, V_0] \subset V_1$ i.e., with $C_{e^1 B_{n+1} \dots B_{2n-1}}^{d^0} = 0$ is called a reduced multialgebra of G and will be symbolized as $|V_0|$.

III. S -EXPANSION OF HIGHER-ORDER LIE ALGEBRAS

In this section we shall review some aspects of the S -expansion procedure introduced in ref. [4]. The main point of this section and of this paper is to show that the generalization of the S -expansion method permits obtaining S -expanded higher-order Lie algebras.

A. S -Expansion of Lie Algebras

The S -expansion method is based on combining the structure constants of the Lie algebra $(\mathcal{G}, [,])$ with the inner law of a semigroup S to define the Lie bracket of a new, S -expanded algebra. Let $S = \{\lambda_\alpha\}$ be a finite Abelian semigroup endowed with a commutative and associative composition law $S \times S \rightarrow S$, $(\lambda_\alpha, \lambda_\beta) \mapsto \lambda_\alpha \lambda_\beta = K_{\alpha\beta}^\gamma \lambda_\gamma$. Let the pair $(\mathcal{G}, [,])$ a Lie algebra where G is a finite dimensional vector space, with basis $\{T_A\}_{A=1}^{\dim \mathcal{G}}$, over the field K ; and $[,]$ is a ruler of composition $G \times G \rightarrow G$, $(T_{A_i}, T_{A_j}) \rightarrow [T_{A_i}, T_{A_j}] = C_{A_i A_j}^{A_k} T_{A_k}$. The direct product $G = S \otimes G$ is defined as the Cartesian product set

$$\mathfrak{G} = S \times \mathcal{G} = \{T_{(A,\alpha)} = \lambda_\alpha T_A : \lambda_\alpha \in S, T_A \in \mathcal{G}\} \quad (21)$$

endowed with a composition law $[,]_S : G \times G \rightarrow G$ defined by

$$[T_{(A,\alpha)}, T_{(B,\beta)}]_S =: \lambda_\alpha \lambda_\beta [T_A, T_B] = K_{\alpha\beta}^\gamma C_{AB}^C \lambda_\gamma T_C = C_{(A,\alpha)(B,\beta)}^{(C,\gamma)} T_{(C,\gamma)}. \quad (22)$$

where $T_{(A,\gamma)} = \lambda_\gamma T_A$ is a basis of G . The set (21) with the composition law (22) is called a S -expanded Lie algebra. This algebra is a Lie algebra structure defined over the vector space obtained by taking $ord S$ copies of G

$$\mathfrak{G} : \oplus_{\alpha \in S} W_\alpha \quad (W_\alpha \approx \mathcal{G}, \forall \alpha)$$

$\dim G = ord S \times \dim G$ by means of the structure constants

$$C_{(A,\alpha)(B,\beta)}^{(C,\gamma)} = C_{AB}^C \delta_{\alpha\beta}^\gamma \quad (23)$$

where δ is the Kronecker symbol and the subindex $\alpha, \beta \in S$ denotes the inner composition in S so that $\delta_{\alpha\beta}^\gamma = 1$ when $\alpha\beta = \gamma$ in S and zero otherwise. The constants $C_{(A,\alpha)(B,\beta)}^{(C,\gamma)}$ defined by (23) inherit the symmetry properties of C_{AB}^C of G by virtue of the abelian character of the S -product, and satisfy the Jacobi identity.

In a nutshell, the S -expansion method can be seen as the natural generalization of the Inönü-Wigner contraction, where instead of to multiply the generators by a numerical parameter, we multiply the generator by the elements of a Abelian semigroup.

Theorem 8 *The product $[\cdot]_S$ defined in (22) is also a Lie product because it is linear, antisymmetric and satisfies the Jacobi identity. This product defines a new Lie algebra characterized by the pair $(\mathfrak{G}, [\cdot]_S)$, and is called a S -expanded Lie algebra.*

Proof. Since the S -product is abelian, the product $[\cdot]_S$ defined by (22) inherits the symmetry properties of the product $[\cdot]$ of \mathcal{G} , and satisfies the Jacobi identity. In fact,

$$\begin{aligned}
& [[T_{(A_1, \alpha_1)}, T_{(A_2, \alpha_2)}]_S, T_{(A_3, \alpha_3)}]_S + [[T_{(A_2, \alpha_2)}, T_{(A_3, \alpha_3)}]_S, T_{(A_1, \alpha_1)}]_S \\
& + [[T_{(A_3, \alpha_3)}, T_{(A_1, \alpha_1)}]_S, T_{(A_2, \alpha_2)}]_S \\
& = \frac{1}{1!} \frac{1}{2!} \sum_{\sigma \in S_3} (-1)^{\pi(\sigma)} \left[[T_{(A_{\sigma(1)}, \alpha_{\sigma(1)})}, T_{(A_{\sigma(2)}, \alpha_{\sigma(2)})}]_S, T_{(A_{\sigma(3)}, \alpha_{\sigma(3)})} \right]_S \\
& = \frac{1}{1!} \frac{1}{2!} \sum_{\sigma \in S_3} (-1)^{\pi(\sigma)} \lambda_{\alpha_{\sigma(1)}} \lambda_{\alpha_{\sigma(2)}} \lambda_{\alpha_{\sigma(3)}} \left[[T_{A_{\sigma(1)}}, T_{A_{\sigma(2)}}]_S, T_{A_{\sigma(3)}} \right] \\
& = \frac{1}{1!} \frac{1}{2!} \sum_{\sigma \in S_3} (-1)^{\pi(\sigma)} K_{\alpha_{\sigma(1)} \alpha_{\sigma(2)} \alpha_{\sigma(3)}}^\gamma \lambda_\gamma \left[[T_{A_{\sigma(1)}}, T_{A_{\sigma(2)}}]_S, T_{A_{\sigma(3)}} \right] \\
& = K_{\alpha_1 \alpha_2 \alpha_3}^\gamma \lambda_\gamma \left(\frac{1}{1!} \frac{1}{2!} \sum_{\sigma \in S_3} (-1)^{\pi(\sigma)} \left[[T_{A_{\sigma(1)}}, T_{A_{\sigma(2)}}]_S, T_{A_{\sigma(3)}} \right] \right) = 0
\end{aligned} \tag{24}$$

where we have used the commutativity $(K_{\alpha_{\sigma(1)} \alpha_{\sigma(2)} \alpha_{\sigma(3)}}^\gamma = K_{\alpha_1 \alpha_2 \alpha_3}^\gamma)$ and associativity of the semigroup inner law, and the fact that the product $[\cdot]$ satisfies the Jacobi identity. ■

From (24) we can see that the Jacobi identity of the S -expanded Lie algebra $(S \otimes \mathcal{G}, [\cdot]_S)$

$$\left([[T_{(A_1, \alpha_1)}, T_{(A_2, \alpha_2)}]_S, T_{(A_3, \alpha_3)}]_S + [[T_{(A_2, \alpha_2)}, T_{(A_3, \alpha_3)}]_S, T_{(A_1, \alpha_1)}]_S + [[T_{(A_3, \alpha_3)}, T_{(A_1, \alpha_1)}]_S, T_{(A_2, \alpha_2)}]_S \right) = 0 \tag{25}$$

can be obtained if we multiply the Jacobi identity of the Lie algebra $(\mathcal{G}, [\cdot])$ by $\lambda_{\alpha_1} \lambda_{\alpha_2} \lambda_{\alpha_3}$ or by the 3-selector $K_{\alpha_1 \alpha_2 \alpha_3}^\gamma$:

$$\text{JI}(S \otimes \mathcal{G}, [\cdot]_S) = K_{\alpha_1 \alpha_2 \alpha_3}^\gamma (\text{JI}(\mathcal{G}, [\cdot])) . \tag{26}$$

Similarly, if multiply the Jacobi condition of the Lie algebra $(\mathcal{G}, [\cdot])$

$$\frac{1}{2} \varepsilon_{A_1 A_2 A_3}^{B_1 B_2 B_3} C_{B_1 B_2}^C C_{C B_3}^D = 0 \tag{27}$$

by $K_{\alpha_1\alpha_2\alpha_3}^\beta = K_{\alpha_1\alpha_2}^\gamma K_{\gamma\alpha_3}^\beta$, we obtain the Jacobi condition of the S -expanded Lie algebra $(S \otimes \mathcal{G}, [,]_S)$. In fact,

$$K_{\alpha_1\alpha_2\alpha_3}^\beta \left(\frac{1}{2} \varepsilon_{A_1 A_2 A_3}^{B_1 B_2 B_3} C_{B_1 B_2}^C C_{C B_3}^D \right) = \frac{1}{2} \varepsilon_{A_1 A_2 A_3}^{B_1 B_2 B_3} K_{\alpha_1\alpha_2}^\gamma C_{B_1 B_2}^C K_{\gamma\alpha_3}^\beta C_{C B_3}^D = 0 \quad (28)$$

$$\frac{1}{2} \varepsilon_{A_1 A_2 A_3}^{B_1 B_2 B_3} C_{(B_1, \alpha_1)(B_2, \alpha_2)}^{(C, \gamma)} C_{(C, \gamma)(B_3, \alpha_3)}^{(D, \beta)} = 0. \quad (29)$$

B. S -Expansion of Lie Multialgebras

The S -expansion method is based on combining the structure constants of $(\mathcal{G}, [, \dots,])$ with the inner law of a semigroup S to define the Lie bracket of a new, S -expanded multialgebra. Let $S = \{\lambda_\alpha\}$ be a finite Abelian semigroup endowed with a commutative and associative composition law $S \times S \rightarrow S$, $(\lambda_\alpha, \lambda_\beta) \mapsto \lambda_\alpha \lambda_\beta = K_{\alpha\beta}^\gamma \lambda_\gamma$. The direct product $G = S \otimes G$ is defined as the cartesian product set

$$\mathfrak{G} = S \times \mathcal{G} = \{T_{(A, \alpha)} = \lambda_\alpha T_A : \lambda_\alpha \in S, T_A \in \mathcal{G}\} \quad (30)$$

with the composition law $[, \dots,]_S : G \times \dots \times G \rightarrow G$, defined by

$$\begin{aligned} [T_{(A_1, \alpha_1)}, \dots, T_{(A_n, \alpha_n)}]_S &= \lambda_{\alpha_1} \dots \lambda_{\alpha_n} [T_{A_1}, \dots, T_{A_n}] \\ [T_{(A_1, \alpha_1)}, \dots, T_{(A_n, \alpha_n)}]_S &= K_{\alpha_1 \dots \alpha_n}^\gamma C_{A_1 \dots A_n}^C \lambda_\gamma T_C = C_{(A_1, \alpha_1) \dots (A_n, \alpha_n)}^{(C, \gamma)} T_{(C, \gamma)} \end{aligned} \quad (31)$$

where $T_{(A_i, \alpha_i)} \in G$, $\forall i = 1, \dots, n$, and $C_{(A_1, \alpha_1) \dots (A_n, \alpha_n)}^{(C, \gamma)} = K_{\alpha_1 \dots \alpha_n}^\gamma C_{A_1 \dots A_n}^C$.

The set $G = S \times G$ (30) with the composition law (31) define a new Lie multialgebra which will be called S -expanded Lie multialgebra. This algebra is a Lie algebra structure defined over the vector space obtained by taking S copies of G by means of the structure constant $C_{(A_1, \alpha_1) \dots (A_n, \alpha_n)}^{(C, \gamma)} = K_{\alpha_1 \dots \alpha_n}^\gamma C_{A_1 \dots A_n}^C$ where $K_{\alpha_1 \dots \alpha_n}^\gamma = K_{\alpha_1 \dots \alpha_{n-1}}^\sigma K_{\sigma \alpha_n}^\gamma$. The structure constants $C_{(A_1, \alpha_1) \dots (A_n, \alpha_n)}^{(C, \gamma)}$ defined in (31) inherit the symmetry properties of $C_{A_1 \dots A_n}^C$ of G by virtue of the abelian character of the S -product.

Theorem 9 *The product $[, \dots,]_S$ defined in (31) is multilinear, antisymmetric and satisfies the generalized Jacobi identity (GJI).*

$$a \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[[T_{(A_{\sigma(1)}, \alpha_{\sigma(1)})}, \dots, T_{(A_{\sigma(n)}, \alpha_{\sigma(n)})}]_S, T_{(A_{\sigma(n+1)}, \alpha_{\sigma(n+1)})}, \dots, T_{(A_{\sigma(2n-1)}, \alpha_{\sigma(2n-1)})}]_S = 0 \quad (32)$$

where

$$a = \frac{1}{(n-1)!} \frac{1}{n!}$$

Proof. Since the S -product is abelian, the product $[\dots]_S$ defined by (31) inherits the symmetry properties of the product $[\dots]$ of $(\mathcal{G}, [\dots])$, and satisfies the generalized Jacobi identity. In fact,

$$\begin{aligned} & \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[\left[T_{(A_{\sigma(1)}, \alpha_{\sigma(1)})}, \dots, T_{(A_{\sigma(n)}, \alpha_{\sigma(n)})} \right]_S, T_{(A_{\sigma(n+1)}, \alpha_{\sigma(n+1)})}, \dots, T_{(A_{\sigma(2n-1)}, \alpha_{\sigma(2n-1)})} \right]_S \\ &= \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \lambda_{\alpha_{\sigma(1)}} \dots \lambda_{\alpha_{\sigma(2n-1)}} \left[\left[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}} \right], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] \\ &= \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} K_{\alpha_{\sigma(1)} \dots \alpha_{\sigma(2n-1)}}^{\gamma} \lambda_{\gamma} \left[\left[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}} \right], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] \\ &= K_{\alpha_1 \dots \alpha_{2n-1}}^{\gamma} \lambda_{\gamma} \left(\sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[\left[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}} \right], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] \right) = 0, \end{aligned} \quad (33)$$

where we have used the commutativity $K_{\alpha_{\sigma(1)} \dots \alpha_{\sigma(2n-1)}}^{\gamma} = K_{\alpha_1 \dots \alpha_{2n-1}}^{\gamma}$ and associativity of the semigroup inner law, and the fact that the product $[\dots]$ satisfies the generalized Jacobi identity. ■

From (33) we can see that the Jacobi identity of the S -expanded Lie multialgebra $(S \otimes \mathcal{G}, [\dots]_S)$ can be obtained if we multiply the generalized Jacobi identity of the Lie multialgebra $(\mathcal{G}, [\dots])$ by $K_{\alpha_1 \dots \alpha_{2n-1}}^{\gamma}$.

Similarly, if we multiply the generalized Jacobi condition of the Lie algebra $(\mathcal{G}, [\dots])$

$$\varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} C_{B_1 \dots B_n}^C C_{CB_{n+1} \dots B_{2n-1}}^D = 0 \quad (34)$$

by $K_{\alpha_1 \dots \alpha_{2n-1}}^{\beta} = K_{\alpha_1 \dots \alpha_n}^{\gamma} K_{\gamma \alpha_{n+1} \dots \alpha_{2n-1}}^{\beta}$, we obtain the generalized Jacobi condition of the S -expanded Lie multialgebra $(\mathfrak{G}, [\dots]_S)$. In fact,

$$K_{\alpha_1 \dots \alpha_{2n-1}}^{\beta} \left(\varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} C_{B_1 \dots B_n}^C C_{CB_{n+1} \dots B_{2n-1}}^D \right) = 0 \quad (35)$$

$$\begin{aligned} & \varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} K_{\alpha_1 \dots \alpha_n}^{\gamma} C_{B_1 \dots B_n}^C K_{\gamma \alpha_{n+1} \dots \alpha_{2n-1}}^{\beta} C_{CB_{n+1} \dots B_{2n-1}}^D = 0 \\ & \varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} C_{(B_1, \alpha_1) \dots (B_n, \alpha_n)}^{(C, \gamma)} C_{(C, \gamma)(B_{n+1}, \alpha_{n+1}) \dots (B_{2n-1}, \alpha_{n+1})}^D = 0. \end{aligned} \quad (36)$$

C. Multialgebra 0_S -Reduced

When the semigroup has a zero element $0_S \in S$, it plays a somewhat peculiar role in the S -expanded Lie multialgebra. Let us span S in nonzero elements $\lambda_i, i = 0, \dots, N$, and a zero

element $\lambda_{N+1} = 0_S$, i.e.,

$$S = \left\{ \underbrace{\lambda_0, \lambda_1, \dots, \lambda_N}_{\lambda_i}, \underbrace{\lambda_{N+1}}_{0_S} \right\}. \quad (37)$$

Then, the 2-selector satisfies

$$\begin{aligned} K_{N+1, i_2, \dots, i_n}^j &= K_{\underbrace{N+1, \dots, N+1}_r, i_{r+1}, \dots, i_n}^j = K_{\underbrace{N+1, \dots, N+1}_r, i_{r+1}, \dots, i_n}^{N+1} = \dots = K_{N+1, \dots, N+1}^j = 0 \\ K_{N+1, i_2, \dots, i_n}^{N+1} &= K_{N+1, \dots, N+1}^{N+1} = 1. \end{aligned} \quad (38)$$

Therefore, the S -expanded multialgebra $(\mathfrak{G}, [\dots]_S)$ can be split as

$$\begin{aligned} [T_{(A_1, i_1)}, \dots, T_{(A_n, i_n)}]_S &= K_{i_1, \dots, i_n}^k C_{A_1 \dots A_n}^C T_{(C, k)} + K_{i_1, \dots, i_n}^{N+1} C_{A_1, \dots, A_n}^{N+1} T_{(C, N+1)} \\ [T_{(A_1, N+1)}, T_{(A_2, i_2)}, \dots, T_{(A_n, i_n)}]_S &= C_{A_1, \dots, A_n} T_{(C, N+1)} \\ &\vdots \\ [T_{(A_1, N+1)}, \dots, T_{(A_r, N+1)}, T_{(A_{r+1}, i_{r+1})}, \dots, T_{(A_n, i_n)}]_S &= C_{A_1, \dots, A_n} T_{(C, N+1)} \\ &\vdots \\ [T_{(A_1, N+1)}, \dots, T_{(A_n, N+1)}]_S &= C_{A_1, \dots, A_n} T_{(C, N+1)}. \end{aligned} \quad (39)$$

From (39) we can see that $(\mathfrak{G}, [\dots]_S)$ can be written as $\mathfrak{G} = V_0 \oplus V_1$, with $V_0 = \{T_{(A, i)}\}$, $V_1 = \{T_{(A, N+1)}\}$. From (39) we also see that

$$[V_1, V_0, \dots, V_0]_S \subset V_1 \quad (40)$$

$$\left[\underbrace{V_1, \dots, V_1}_{r\text{-times}}, V_0, \dots, V_0 \right]_S \subset V_1, \quad \text{con } r = 1, \dots, n. \quad (41)$$

This means that the commutation relations

$$[T_{(A_1, i_1)}, \dots, T_{(A_n, i_n)}]_S = K_{i_1, \dots, i_n}^k C_{A_1 \dots A_n}^C T_{(C, k)}$$

are those of a reduced Lie multialgebra $(\mathfrak{G}, [\dots]_S)$. From (39) we see that the reduction procedure in this particular case is equivalent to imposing the condition

$$T_{(C, N+1)} = 0_S T_C = 0.$$

The above considerations motivate the following definition:

Definition 10 Let S be an Abelian semigroup with a zero element $0_S \in S$, and let $(S \otimes \mathcal{G}, [\dots])$ be an S -expanded multialgebra. The multialgebra obtained by imposing the condition $0_S T_A = 0$ on \mathfrak{G} is called a 0_S -reduced multialgebra of \mathfrak{G} .

IV. S-EXPANSION OF SUBMULTIALGEBRAS

In this section is shown that there are at least two ways of extracting smaller multialgebras from $(S \otimes \mathcal{G}, [, \dots,])$. The first one gives rise to a "resonant submultialgebra" while the second produces reduced multialgebras of a resonant submultialgebra.

A. Resonant submultialgebras

The general problem of finding submultialgebras from an S -expanded multialgebra is a nontrivial one, which is met and solved in this section. In order to provide a solution, one must have some information about the subspace structure of $\mathcal{G}, [, \dots,]$. This information is encoded in the following way:

Let $\mathcal{G} = \oplus_{p \in I} V_p$ be a decomposition of \mathcal{G} in subspaces V_p , where I is a set of indices. For each $(p_1, \dots, p_n) \in I$ it is always possible to define $i_{(p_1, \dots, p_n)} \subset I$ such that

$$[V_{p_1}, \dots, V_{p_n}] \subset \bigoplus_{r \in i_{(p_1, \dots, p_n)}} V_r. \quad (42)$$

In this way, the subsets $\{i_{(p_1, \dots, p_n)}\}$ store the information on the subspace structure of \mathcal{G} .

As for the Abelian semigroup S , this can always be decomposed as $S = \cup_{p \in I} S_p$, where $S_p \subset S$. In principle, this decomposition is completely arbitrary; however, using the product from definition (2.2) of ref. [4], it is sometimes possible to pick out a very particular choice of subset decomposition. This choice is the subject of the following definition:

Definition 11 *Let $\mathcal{G} = \oplus_{p \in I} V_p$ be a decomposition of \mathcal{G} in subspaces V_p , with a structure described by the subsets $i_{(p_1, \dots, p_n)}$, as in Eq.(42). Let $S = \cup_{p \in I} S_p$ be a subset decomposition of the Abelian semigroup S such that*

$$S_{p_1} \times S_{p_2} \times \dots \times S_{p_n} \subset \bigcap_{r \in i_{(p_1, \dots, p_n)}} S_r. \quad (43)$$

When such a subset decomposition $S = \cup_{p \in I} S_p$ exists, then we say that this decomposition is in resonance with the subspace decomposition of $\mathcal{G} = \oplus_{p \in I} V_p$.

Theorem 12 *Let $\mathcal{G} = \oplus_{p \in I} V_p$ be a subspace decomposition of \mathcal{G} , with a structure described by Eq. (42), and let $S = \cup_{p \in I} S_p$ be a resonant subset decomposition of the Abelian semigroup*

S , with the structure given in Eq.(43). Define the subspaces W_p of $\mathfrak{G} = S \otimes \mathcal{G}$,

$$W_p = S_p \otimes V_p, \quad p \in I. \quad (44)$$

Then,

$$\mathfrak{G}_R = \oplus_{p \in I} W_p \quad (45)$$

is called a resonant subalgebra of the S -expanded multialgebra $\mathfrak{G} = S \otimes \mathcal{G}$.

Proof. Using Eqs. (42) and (43) we have

$$\begin{aligned} [W_{p_1}, \dots, W_{p_n}]_S &= [S_{p_1} \otimes V_{p_1}, \dots, S_{p_n} \otimes V_{p_n}]_S = (S_{p_1} \times \dots \times S_{p_n}) \otimes [V_{p_1}, \dots, V_{p_n}] \\ &\subset \left(\bigcap_{s \in i_{(p_1, \dots, p_n)}} S_s \right) \otimes \left(\bigoplus_{r \in i_{(p_1, \dots, p_n)}} V_r \right) = \bigoplus_{r \in i_{(p_1, \dots, p_n)}} \left(\bigcap_{s \in i_{(p_1, \dots, p_n)}} S_s \right) \otimes V_r. \end{aligned} \quad (46)$$

But, it is clear that for each $r \in i_{(p_1, \dots, p_n)}$ one can write

$$\bigcap_{s \in i_{(p_1, \dots, p_n)}} S_s \subset S_r. \quad (47)$$

Then,

$$\begin{aligned} [W_{p_1}, \dots, W_{p_n}]_S &\subset \bigoplus_{r \in i_{(p_1, \dots, p_n)}} S_r \otimes V_r = \bigoplus_{r \in i_{(p_1, \dots, p_n)}} W_r \\ [W_{p_1}, \dots, W_{p_n}]_S &\subset \bigoplus_{r \in i_{(p_1, \dots, p_n)}} S_r \otimes V_r = \bigoplus_{r \in i_{(p_1, \dots, p_n)}} W_r \\ [W_{p_1}, \dots, W_{p_n}]_S &\subset \bigoplus_{r \in I} W_r = \mathfrak{G}_R \end{aligned} \quad (48)$$

■

Therefore, the algebra closes and \mathfrak{G}_R is a submultialgebra of \mathfrak{G} .

This theorem translates the difficult problem of finding subalgebras from an S -expanded algebra $\mathfrak{G} = S \otimes \mathfrak{g}$ into that of finding a resonant partition for the semigroup S .

Denoting the basis of V_{p_i} by $\{T_{a_{p_i}}\}$, $\lambda_{\alpha_{p_i}} \in S_{p_i}$ and $T_{(a_{p_i}, \alpha_{p_i})} = \lambda_{\alpha_{p_i}} T_{a_{p_i}} \in W_{p_i}$ one can write

$$\left[T_{(a_{p_1}, \alpha_{p_1})}, \dots, T_{(a_{p_n}, \alpha_{p_n})} \right]_S = C_{(a_{p_1}, \alpha_{p_1}) \dots (a_{p_n}, \alpha_{p_n})}^{(c_r, \gamma_r)} T_{(c_r, \gamma_r)},$$

which means that the structure constants of the resonant submultialgebra are given by

$$C_{(a_{p_1}, \alpha_{p_1}) \dots (a_{p_n}, \alpha_{p_n})}^{(c_r, \gamma_r)} = K_{\alpha_{p_1} \dots \alpha_{p_n}}^{\gamma_r} C_{a_{p_1} \dots a_{p_n}}^{c_r}.$$

An interesting fact is that the S -expanded multialgebra "subspace structure" encoded in $i_{(p_1, \dots, p_n)}$ is the same as in the original multialgebra, as can be observed from Eq. (48).

B. Reduced Multialgebras of a Resonant Submultialgebra

The following theorem provides necessary conditions under which a reduced multialgebra can be extracted from a resonant subalgebra:

Theorem 13 *Let $\mathfrak{G}_R = \oplus_{p \in I} S_p \otimes V_p$ be a resonant submultialgebra $(\mathfrak{G}, [\dots]_S)$, i.e., let Eqs. (42) and (43) be satisfied. Let $S_p = \hat{S}_p \cup \check{S}_p$ be a partition of the subsets $S_p \subset S$ such that*

$$\check{S}_{p_i} \cap \hat{S}_{p_i} = \phi \quad (49)$$

$$\hat{S}_{p_1} \times \check{S}_{p_2} \times \dots \times \check{S}_{p_n} \subset \bigcap_{r \in i(p_1, \dots, p_n)} \hat{S}_r. \quad (50)$$

The conditions (49) and (50) induce the decomposition $\mathfrak{G}_R = \check{\mathfrak{G}}_R \oplus \hat{\mathfrak{G}}_R$ on the resonant subalgebra, where

$$\check{\mathfrak{G}}_R = \oplus_{p \in I} \check{S}_p \otimes V_p \quad (51)$$

$$\hat{\mathfrak{G}}_R = \oplus_{p \in I} \hat{S}_p \otimes V_p. \quad (52)$$

When conditions (49) and (50) hold, then

$$\left[\hat{\mathfrak{G}}_R, \check{\mathfrak{G}}_R, \dots, \check{\mathfrak{G}}_R \right]_S \subset \hat{\mathfrak{G}}_R \quad (53)$$

and therefore $|\check{\mathfrak{G}}_R|$ corresponds to a reduced algebra of \mathfrak{G}_R .

Proof. $\hat{W}_{p_i} = \hat{S}_{p_i} \otimes V_{p_i}$ and $\check{W}_{p_i} = \check{S}_{p_i} \otimes V_{p_i}$. Then, using condition (50), we have:

$$\begin{aligned} \left[\hat{W}_{p_1}, \check{W}_{p_2}, \dots, \check{W}_{p_n} \right]_S &= \left[\hat{S}_{p_1} \otimes V_{p_1}, \check{S}_{p_2} \otimes V_{p_2}, \dots, \check{S}_{p_n} \otimes V_{p_n} \right]_S \\ &= \left(\hat{S}_{p_1} \times \check{S}_{p_2} \times \dots \times \check{S}_{p_n} \right) \otimes [V_{p_1}, V_{p_2}, \dots, V_{p_n}] \\ &\subset \left(\bigcap_{s \in i(p_1, \dots, p_n)} \hat{S}_s \right) \otimes \left(\bigoplus_{r \in i(p_1, \dots, p_n)} V_r \right) \\ &= \bigoplus_{r \in i(p_1, \dots, p_n)} \left(\bigcap_{s \in i(p_1, \dots, p_n)} \hat{S}_s \right) \otimes V_r. \end{aligned}$$

For each $r \in i(p_1, \dots, p_n)$ we have

$$\bigcap_{s \in i(p_1, \dots, p_n)} \hat{S}_s \subset \hat{S}_r$$

so that,

$$\begin{aligned} \left[\hat{W}_{p_1}, \check{W}_{p_2}, \dots, \check{W}_{p_n} \right]_S &\subset \bigoplus_{r \in i(p_1, \dots, p_n)} \hat{S}_r \otimes V_r = \bigoplus_{r \in i(p_1, \dots, p_n)} \hat{W}_r \\ &\subset \bigoplus_{r \in I} \hat{W}_r = \hat{\mathfrak{G}}_R. \end{aligned}$$

Thus $\left[\hat{W}_{p_1}, \check{W}_{p_2}, \dots, \check{W}_{p_n} \right]_S \subset \hat{\mathfrak{G}}_R$, i.e.,

$$\left[\hat{\mathfrak{G}}_R, \check{\mathfrak{G}}_R, \dots, \check{\mathfrak{G}}_R \right]_S \subset \hat{\mathfrak{G}}_R$$

and therefore $|\check{\mathfrak{G}}_R|$ is a reduced algebra of \mathfrak{G}_R . ■

The structure constants for the reduced algebra $|\check{\mathfrak{G}}_R|$ are given by,

$$C_{(a_{p_1}, \alpha_{p_1}) \dots (a_{p_n}, \alpha_{p_n})}^{(c_r, \gamma_r)} = K_{\alpha_{p_1} \dots \alpha_{p_n}}^{\gamma_r} C_{a_{p_1} \dots a_{p_n}}^{c_r}$$

with α_{p_i}, γ_r such that $\lambda_{\alpha_{p_i}} \in \check{S}_{p_i}$ y $\lambda_{\gamma_r} \in \check{S}_{p_r}$.

C. $S_E^{(N)}$ -Expansion of Multialgebras

Definition 14 Let us define $S_E^{(N)}$ as the semigroup of elements [8]

$$S_E^{(N)} = \{\lambda_\alpha, \alpha = 0, \dots, N+1\} \quad (54)$$

provided with a multiplication rule

$$\lambda_\alpha \lambda_\beta = \lambda_{H_{N+1}(\alpha+\beta)} = \delta_{H_{N+1}(\alpha+\beta)}^\gamma \lambda_\gamma \quad (55)$$

where H_{N+1} is defined as the function

$$H_n(x) = \begin{cases} x, & \text{when } x < n, \\ n, & \text{when } x \geq n. \end{cases} \quad (56)$$

The two-selectors for $S_E^{(N)}$ read

$$K_{\alpha\beta}^\gamma = \delta_{H_{N+1}(\alpha+\beta)}^\gamma$$

where δ_σ^ρ is the Kronecker delta.

The multiplication rule (55) can be directly generalized to

$$\begin{aligned}\lambda_{\alpha_1} \dots \lambda_{\alpha_n} &= \lambda_{H_{N+1}(\alpha_1 + \dots + \alpha_n)} = \delta_{H_{N+1}(\alpha_1 + \dots + \alpha_n)}^\gamma \lambda_\gamma \\ K_{\alpha_1 \dots \alpha_n}^\gamma &= \delta_{H_{N+1}(\alpha_1 + \dots + \alpha_n)}^\gamma.\end{aligned}\tag{57}$$

From Eq.(55), we have that λ_{N+1} is the zero element in $S_E^{(N)}$, i.e., $\lambda_{N+1} = 0_S$.

The corresponding S -expanded multialgebra is given by the following commutation relation:

$$[T_{(A_1, \alpha_1)}, \dots, T_{(A_n, \alpha_n)}]_S = \delta_{H_{N+1}(\alpha_1 + \dots + \alpha_n)}^\gamma C_{A_1 \dots A_n}^C T_{(C, \gamma)},\tag{58}$$

which implies that the structure constants for the $S_E^{(N)}$ -expanded multialgebra can be written as

$$C_{(A_1, \alpha_1) \dots (A_n, \alpha_n)}^{(C, \gamma)} = \delta_{H_{N+1}(\alpha_1 + \dots + \alpha_n)}^\gamma C_{A_1 \dots A_n}^C\tag{59}$$

with $\gamma, \alpha_1, \dots, \alpha_n = 0, \dots, N+1$. When the condition of 0_S -reduction is imposed, the Eq.(59) reduces to

$$C_{(A_1, i_1) \dots (A_n, i_n)}^{(C, k)} = \delta_{H_{N+1}(i_1 + \dots + i_n)}^k C_{A_1 \dots A_n}^C.$$

V. COMMENTS

We have shown that the successful S -expansion of the Lie algebras method, developed in ref. [4], can be generalized so as to obtain expanded higher-order Lie algebras.

The main results of this paper are: the generalizations of the definitions of Lie subalgebras and reduced Lie algebras to higher-order Lie subalgebras and higher-order reduced Lie algebras; to generalize the S -expansion method and to show that it is possible to obtain higher-order expanded Lie algebras, as well as to probe that under determined conditions can be extracted relevant higher-order Lie subalgebras from the S -expanded higher-order Lie algebras.

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VI. APPENDIX A

In this appendix we show that the realization (4) of the multibracket satisfies the identity

$$\begin{aligned} & \frac{1}{(n-1)!} \frac{1}{n!} \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[\left[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}} \right], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] \\ &= \begin{cases} 0, & n \text{ even} \\ n [T_{A_1}, \dots, T_{A_{2n-1}}], & n \text{ odd.} \end{cases} \end{aligned} \quad (60)$$

which can be re-written in the following way:

$$\begin{aligned} & \frac{1}{(n-1)!} \frac{1}{n!} \varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} \left[[T_{B_1}, \dots, T_{B_n}], T_{B_{n+1}}, \dots, T_{B_{2n-1}} \right] \\ &= \begin{cases} 0, & n \text{ even} \\ nn! (n-1)! [T_{A_1}, \dots, T_{A_{2n-1}}], & n \text{ odd.} \end{cases} \end{aligned} \quad (61)$$

In fact, if

$$\varphi = \varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} \left[[T_{B_1}, \dots, T_{B_n}], T_{B_{n+1}}, \dots, T_{B_{2n-1}} \right], \quad (62)$$

then

$$\begin{aligned} \varphi &= \varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} \left[\varepsilon_{B_1 \dots B_n}^{C_1 \dots C_n} T_{C_1} \dots T_{C_n}, T_{B_{n+1}}, \dots, T_{B_{2n-1}} \right] \\ &= \varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} \varepsilon_{B_1 \dots B_n}^{C_1 \dots C_n} [T_{C_1} \dots T_{C_n}, T_{B_{n+1}}, \dots, T_{B_{2n-1}}] \\ &= n! \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_n B_{n+1} \dots B_{2n-1}} [T_{C_1} \dots T_{C_n}, T_{B_{n+1}}, \dots, T_{B_{2n-1}}] \end{aligned} \quad (63)$$

where we have used Eq.(4) and the property

$$\varepsilon_{h_1 \dots h_r}^{i_1 \dots i_r} B^{h_1 \dots h_r} = r! B^{i_1 \dots i_r}. \quad (64)$$

We consider now the multibracket $[T_{C_1} \dots T_{C_n}, T_{B_{n+1}}, \dots, T_{B_{2n-1}}]$. The expression $T_{C_1} \dots T_{C_n}$ is the matrix product of n elements, and therefore is a mapping onto another element of \mathcal{G} , which must be antisymmetrized together with $T_{B_{n+1}}, \dots, T_{B_{2n-1}}$. Thus, we can write

$$\begin{aligned} & [T_{C_1} \dots T_{C_n}, T_{B_{n+1}}, \dots, T_{B_{2n-1}}] \\ &= \varepsilon_{B_{n+1} \dots B_{2n-1}}^{C_{n+1} \dots C_{2n-1}} \sum_{s=0}^{n-1} (-1)^s T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_1} \dots T_{C_n} T_{C_{n+s+1}} \dots T_{C_{2n-1}} \end{aligned} \quad (65)$$

where the $n - 1$ elements $T_{B_{n+1}}, \dots, T_{B_{2n-1}}$ are antisymmetrized with the contraction with $\varepsilon_{B_{n+1} \dots B_{2n-1}}^{C_{n+1} \dots C_{2n-1}}$ and the element $T_{C_1} \dots T_{C_n}$ is antisymmetrized with \sum . Introducing these results into (63) we have

$$\begin{aligned}
\varphi &= n! \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_n B_{n+1} \dots B_{2n-1}} \varepsilon_{B_{n+1} \dots B_{2n-1}}^{C_{n+1} \dots C_{2n-1}} \\
&\times \sum_{s=0}^{n-1} (-1)^s T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_1} \dots T_{C_n} T_{C_{n+s+1}} \dots T_{C_{2n-1}} \\
&= n! (n-1)! \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} \\
&\times \sum_{s=0}^{n-1} (-1)^s T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_1} \dots T_{C_n} T_{C_{n+s+1}} \dots T_{C_{2n-1}} \\
&= n! (n-1)! \\
&\times \sum_{s=0}^{n-1} (-1)^s \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_1} \dots T_{C_n} T_{C_{n+s+1}} \dots T_{C_{2n-1}}
\end{aligned} \tag{66}$$

where we have used the identity (64). Since

$$\begin{aligned}
&\varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_1} \dots T_{C_n} T_{C_{n+s+1}} \dots T_{C_{2n-1}} \\
&= (-1)^s \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_1} T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_2} \dots T_{C_n} T_{C_{n+s+1}} \dots T_{C_{2n-1}} \\
&= (-1)^s (-1)^s \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_1} T_{C_2} T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_3} \dots T_{C_n} T_{C_{n+s+1}} \dots T_{C_{2n-1}} \\
&\vdots \\
&= (-1)^{ns} \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_1} \dots T_{C_n} T_{C_{n+1}} \dots T_{C_{n+s}} T_{C_{n+s+1}} \dots T_{C_{2n-1}} \\
&= (-1)^{ns} \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_1} \dots T_{C_{2n-1}},
\end{aligned} \tag{67}$$

we have that (66) takes the form

$$\begin{aligned}
\varphi &= n! (n-1)! \sum_{s=0}^{n-1} (-1)^s (-1)^{ns} \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_1} \dots T_{C_{2n-1}} \\
&= n! (n-1)! \varepsilon_{A_1 \dots A_{2n-1}}^{C_1 \dots C_{2n-1}} T_{C_1} \dots T_{C_{2n-1}} \sum_{s=0}^{n-1} (-1)^s (-1)^{ns} \\
&= n! (n-1)! [T_{A_1}, \dots, T_{A_{2n-1}}] \sum_{s=0}^{n-1} (-1)^{s(n+1)}.
\end{aligned}$$

It is direct to check that

$$\sum_{s=0}^{n-1} (-1)^{s(n+1)} = \begin{cases} 0, & \text{for } n \text{ even} \\ n, & \text{for } n \text{ odd} \end{cases}.$$

Using (62) we find

$$\begin{aligned} & \frac{1}{n!} \frac{1}{(n-1)!} \varepsilon_{A_1 \dots A_{2n-1}}^{B_1 \dots B_{2n-1}} \left[[T_{B_1}, \dots, T_{B_n}], T_{B_{n+1}}, \dots, T_{B_{2n-1}} \right] \\ &= \begin{cases} 0, & \text{for } n \text{ even} \\ n [T_{A_1}, \dots, T_{A_{2n-1}}], & \text{for } n \text{ odd} \end{cases} \end{aligned}$$

or

$$\begin{aligned} & \frac{1}{(n-1)!} \frac{1}{n!} \sum_{\sigma \in S_{2n-1}} (-1)^{\pi(\sigma)} \left[[T_{A_{\sigma(1)}}, \dots, T_{A_{\sigma(n)}}], T_{A_{\sigma(n+1)}}, \dots, T_{A_{\sigma(2n-1)}} \right] \\ &= \begin{cases} 0, & \text{for } n \text{ even} \\ n [T_{A_1}, \dots, T_{A_{2n-1}}], & \text{for } n \text{ odd} \end{cases}. \end{aligned}$$

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- [8] where the order of the multialgebra is denoted by n and N denotes the number of elements of the semigroup $S_E^{(N)}$.